

Intensity function  $\lambda(t)$ .

As typical for point processes, our data structure is driven by the arrival of events. We write  $t_i$  for the time at which the i<sup>th</sup> event happened, resulting in data  $Y = (t_1 ... t_n).$ 

Hawkes processes are a particular type of point process we use when events occur in clusters or bursts. They are very popular in the earthquake literature, but are also used to model retweets on Twitter or crimes in a city. The Hawkes process for events  $Y = (t_1 \dots t_n)$  is parametrised by an intensity function  $\lambda(t)$  of the form:  $\lambda(t) = \mu + \sum_{i: t_i < t} K \beta \exp(-\beta(t - t_i)).$ 

There are three parameters: background rate  $\mu$ , area of the spike *K*, and rate of decay of the spike  $\beta$ .

# When data from a Hawkes Processis missing, estimation becomes difficult. ABC can help.

When we collect data, we might not record all of the events correctly. This is particularly prevalent in some of the applications of a Hawkes process. In earthquakes we fail to detect small earthquakes that happen directly after a big one.

Approximate Bayesian Computation provides posterior samples without evaluating the likelihood. We assume that if two data sets are "close", then the parameters that produced those data sets are also similar. We therefore propose a parameter  $\theta^*$ , simulate a data set  $Y^*$  from it, and if the data set is similar to the observed data Y, we accept  $\theta^*$  as a draw from an approximate posterior distribution. When data from a Hawkes process is missing, it is impossible to integrate out the missing events, due to the particular form of the likelihood. This means our likelihood becomes intractable and classic sampling methods cannot be applied.

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"delete" a portion of data (in the grey box).



For our ABC-MCMC approach use seven bespoke summary statistics that determine data. When we compare ABC-MCMC to other methods, only those that take missing data into account perform well.



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